# Chord

A scalable peer-to-peer look-up protocol for internet applications

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# Overview

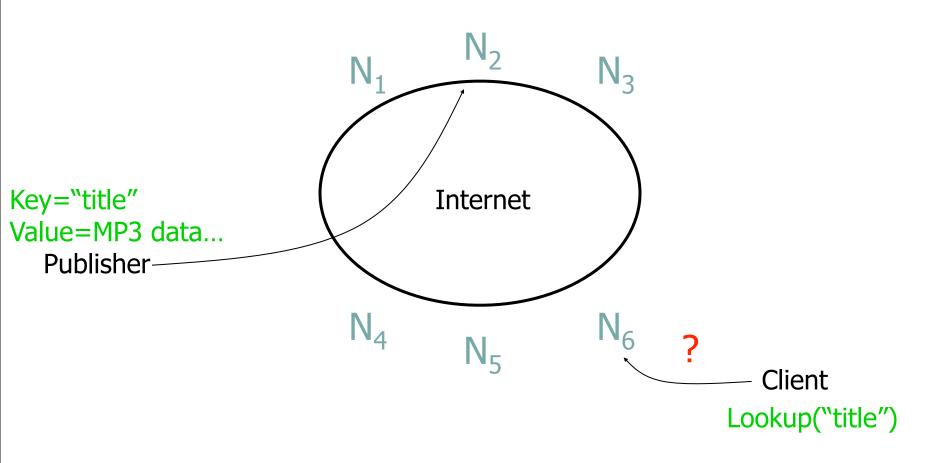
#### Introduction

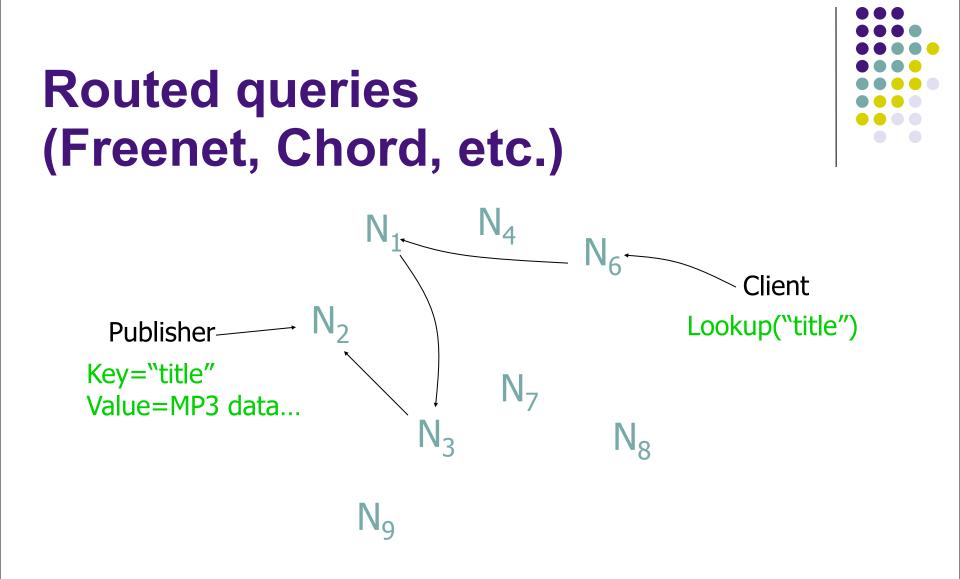
- The Chord Algorithm
  - Construction of the Chord ring
  - Localization of nodes
  - Node joins and stabilization
  - Failure of nodes
- Applications
- Summary
- Questions





# The lookup problem





#### What is Chord?



- Problem addressed: efficient node localization
- Distributed lookup protocol
- Simplicity, provable performance, proven correctness
- Support of just one operation: given a key, Chord maps the key onto a node

# **Chord software**



- 3000 lines of C++ code
- Library to be linked with the application
- provides a lookup(key) function: yields the IP address of the node responsible for the key
- Notifies the node of changes in the set of keys the node is responsible for

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# The Chord algorithm – Construction of the Chord ring



 use Consistent Hash Function assigns each <u>node</u> and each <u>key</u> an m-bit identifier using SHA 1 (Secure Hash Standard).

m = any number <u>big enough</u> to make collisions improbable

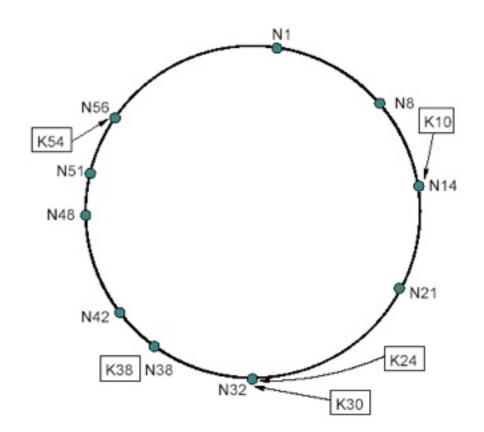
Key identifier = SHA-1(key)

Node identifier = SHA-1(IP address)

- Both are uniformly distributed
- Both exist in the same ID space

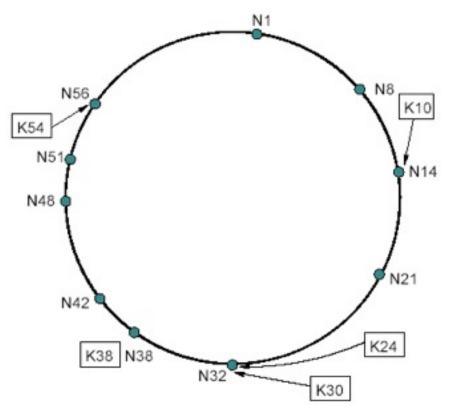
# The Chord algorithm – Construction of the Chord ring

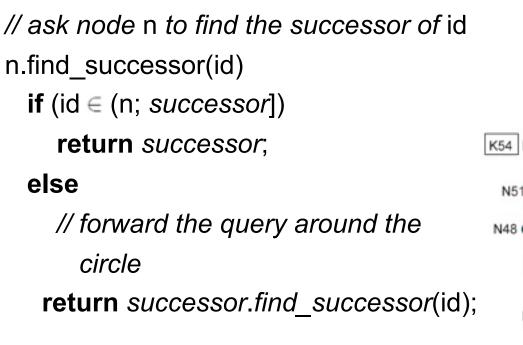
 identifiers are arranged on a identifier circle modulo 2<sup>m</sup> =>
Chord ring



#### The Chord algorithm – Construction of the Chord ring

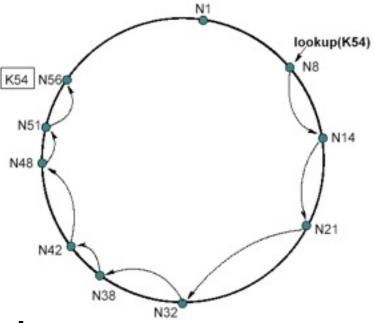
- a key k is assigned to the node whose identifier is equal to or greater than the key's identifier
- this node is called successor(k) and is the first node clockwise from k.





#### => Number of messages linear in the number of nodes !

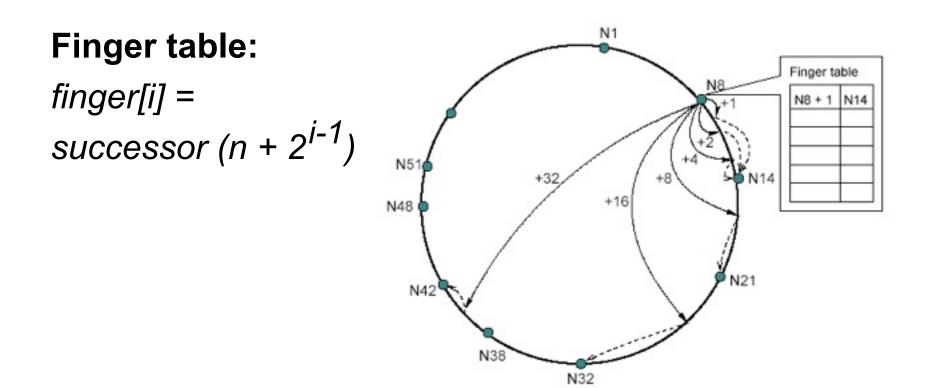




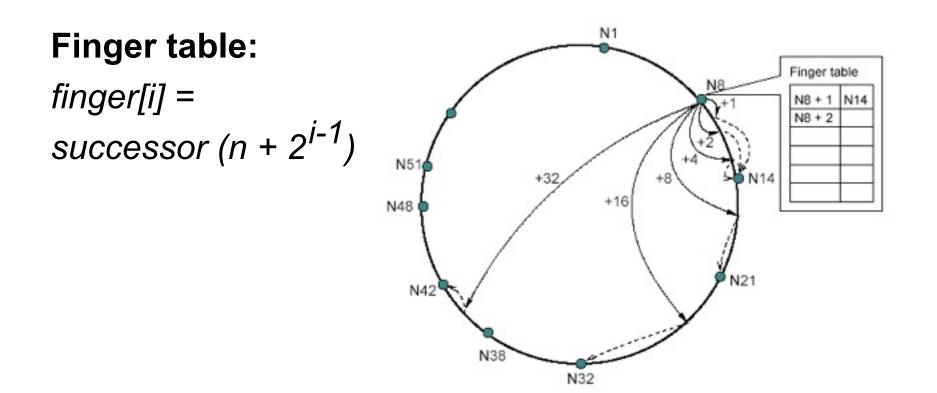


- Additional routing information to accelerate lookups
- Each node n contains a routing table with up to m entries (m: number of bits of the identifiers) => finger table
- ith entry in the table at node n contains the first node s that succeeds n by at least 2<sup>i-1</sup>
- $s = successor(n + 2^{i-1})$
- s is called the i<sup>th</sup> finger of node n

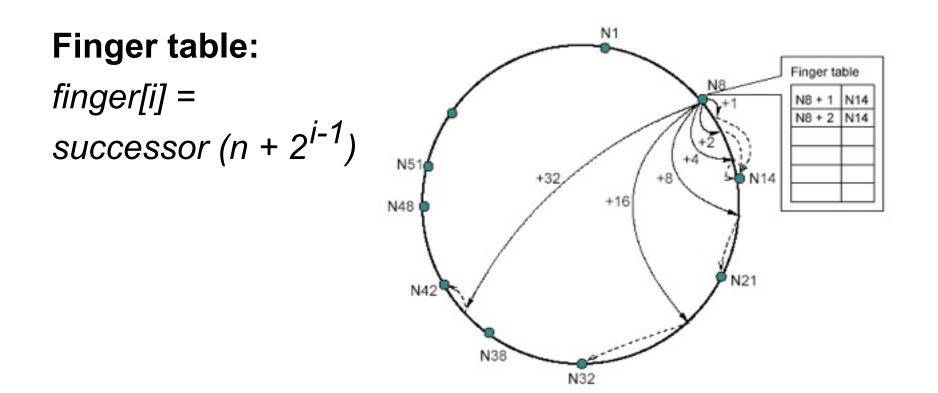




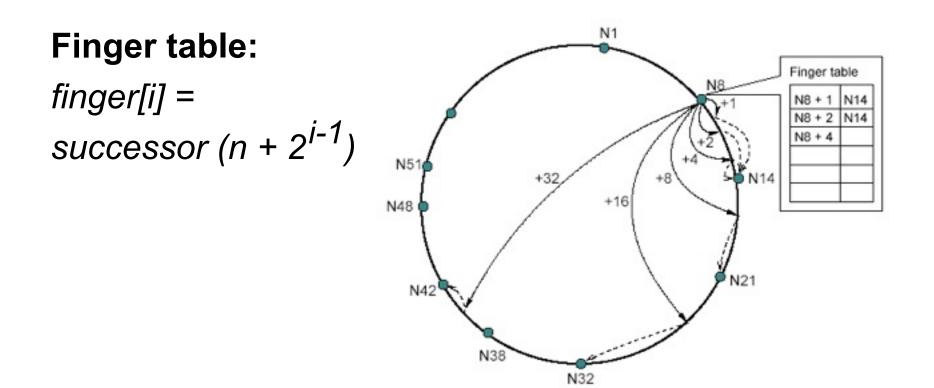




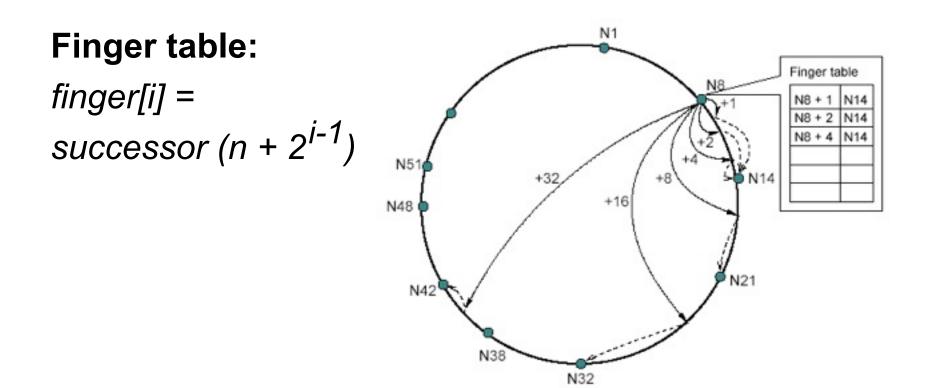




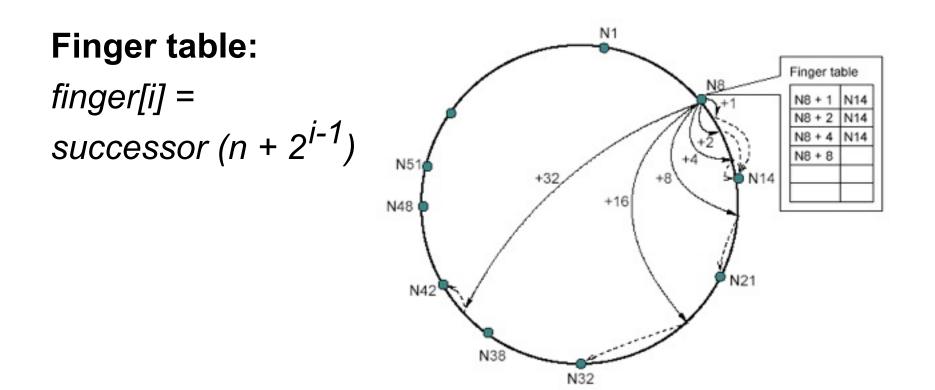




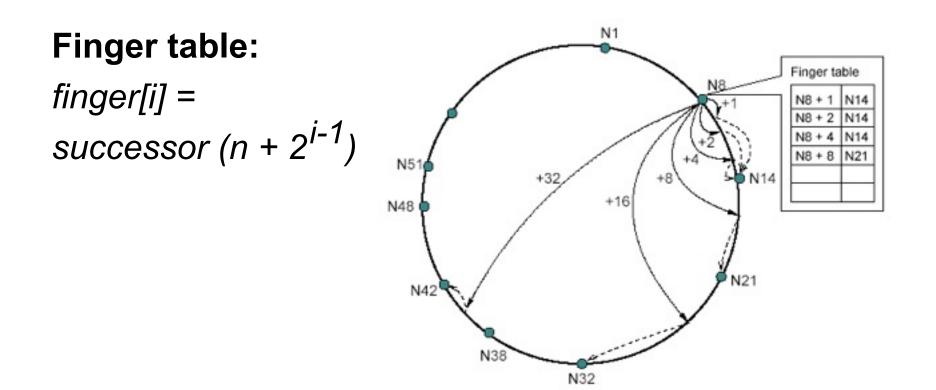




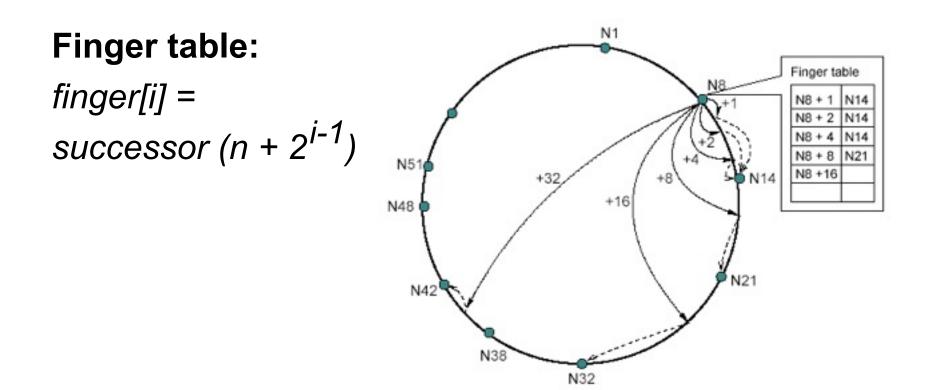




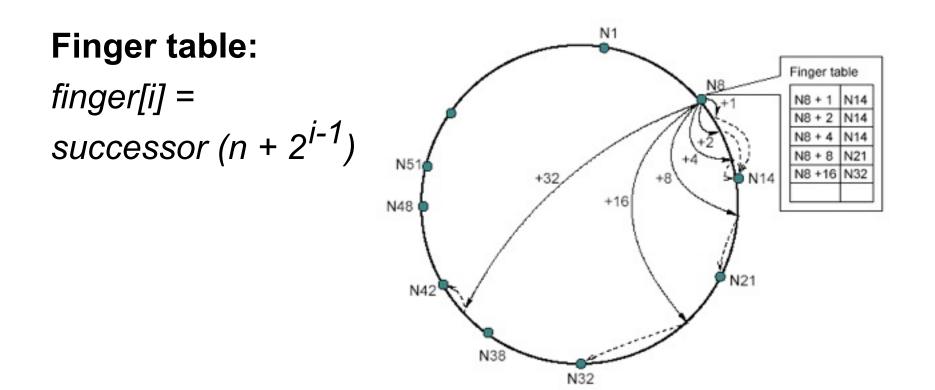




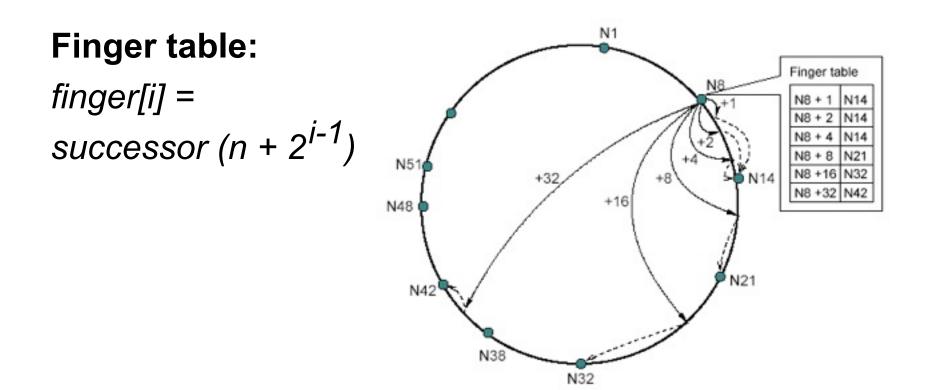








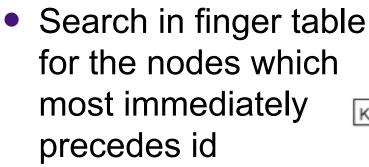






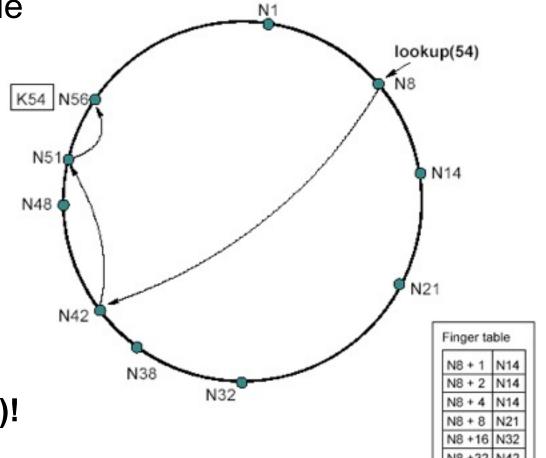
Important characteristics of this scheme:

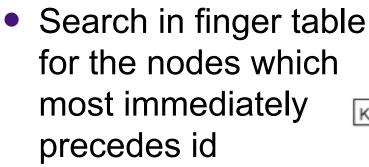
- Each node stores information about only a small number of nodes (m)
- Each nodes knows more about nodes closely following it than about nodes further away
- A finger table generally does not contain enough information to directly determine the successor of an arbitrary key k



 Invoke find\_successor from that node

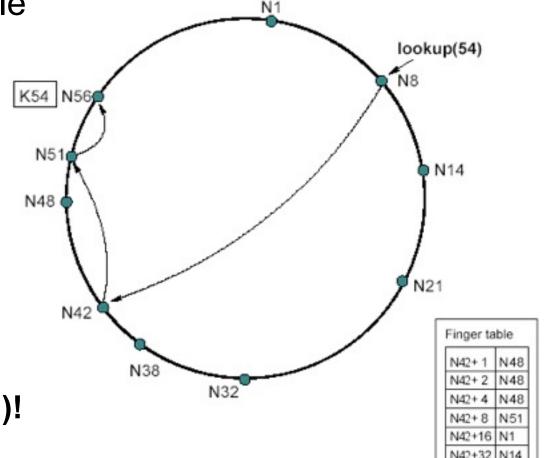
=> Number of messages O(log N)!



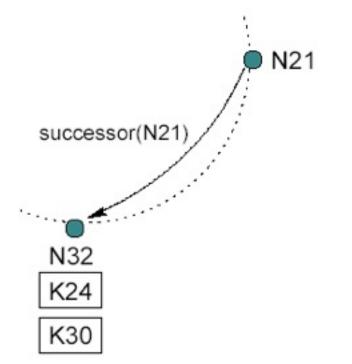


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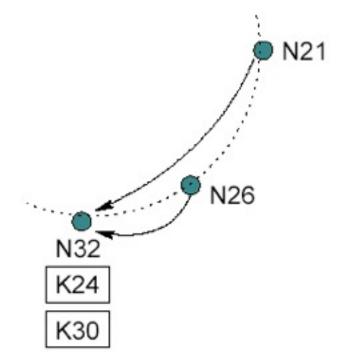
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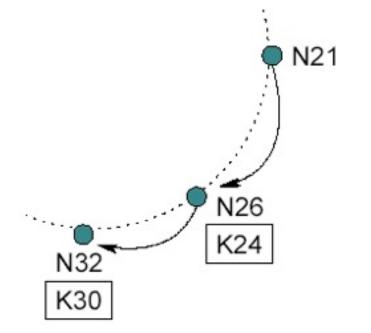














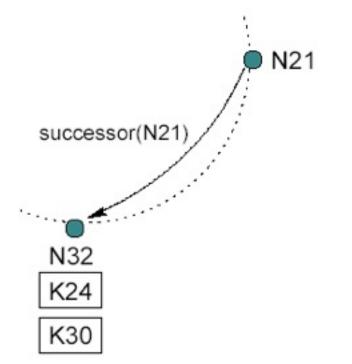
- To ensure correct lookups, all successor pointers must be up to date
- => stabilization protocol running periodically in the background
- Updates finger tables and successor pointers



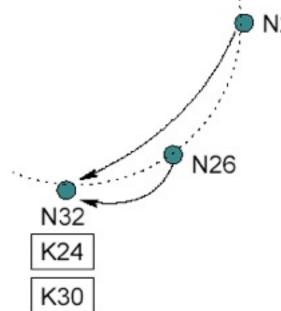
Stabilization protocol:

- Stabilize(): n asks its successor for its predecessor p and decides whether p should be n's successor instead (this is the case if p recently joined the system).
- Notify(): notifies n's successor of its existence, so it can change its predecessor to n
- Fix\_fingers(): updates finger tables

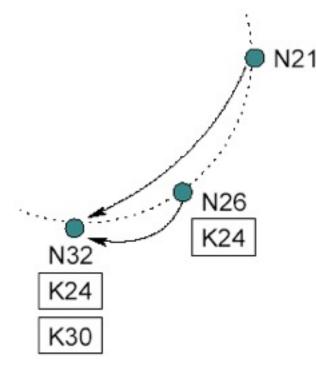








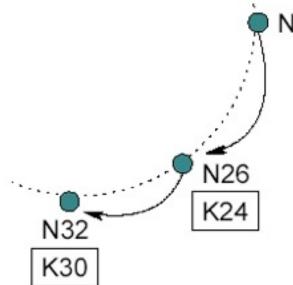
- <sup>21</sup> N26 joins the system
  - N26 acquires N32 as its successor
  - N26 notifies N32
  - N32 acquires N26 as its predecessor



N26 copies keys

• N21 runs stabilize() and asks its successor N32 for its predecessor which is N26.





N21 • N21 acquires N26 as its successor

- N21 notifies N26 of its existence
- N26 acquires N21 as predecessor

# The Chord algorithm – Impact of node joins on lookups

Finger table

N8 + 2

N8 + 4

N8 + 8

N8 +16 N32

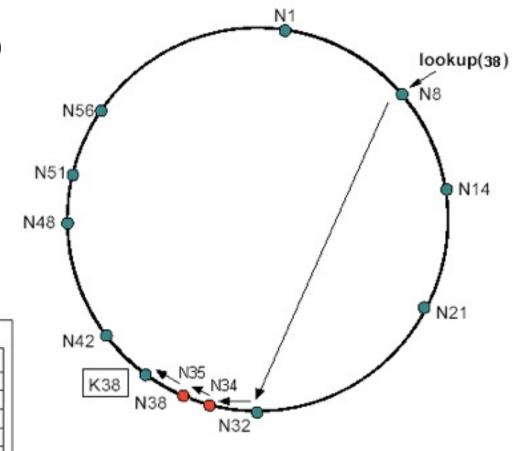
N14

N14

N14

N21

- All finger table entries are correct => O(log N) lookups
- Successor pointers correct, but fingers inaccurate => correct but slower lookups



# The Chord algorithm – Impact of node joins on lookups



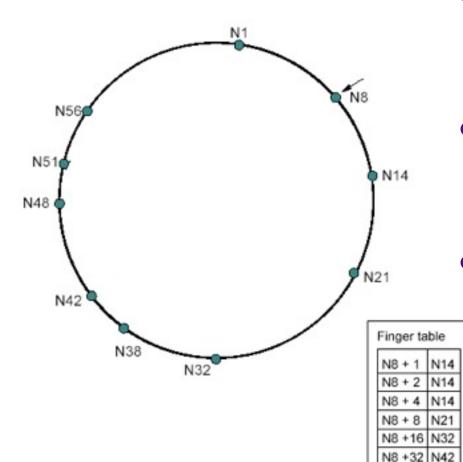
- Incorrect successor pointers => lookup might fail, retry after a pause
- But still correctness!

# The Chord algorithm – Impact of node joins on lookups



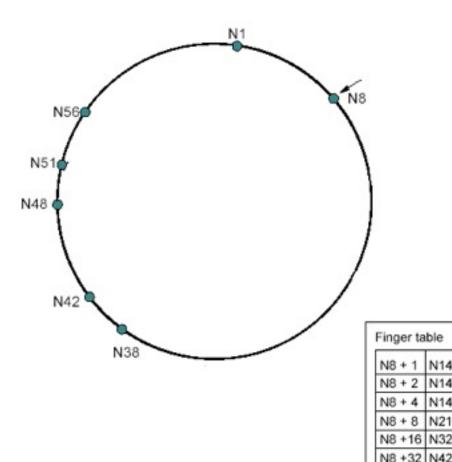
- Stabilization completed => no influence on performance
- Only for the negligible case that a large number of nodes joins between the target's predecessor and the target, the lookup is slightly slower
- No influence on performance as long as fingers are adjusted faster than the network doubles in size





- Correctness relies on correct successor pointers
- What happens, if N14, N21, N32 fail simultaneously?
- How can N8 acquire N38 as successor?



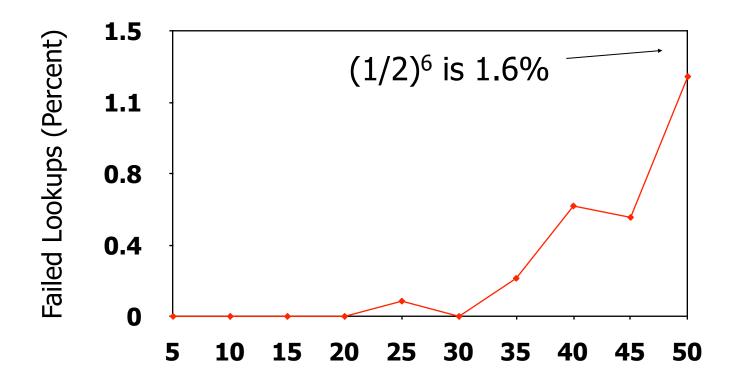


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- Each node maintains a successor list of size r
- If the network is initially stable, and every node fails with probability ½, find\_successor still finds the closest living successor to the query key and the expected time to execute find\_succesor is O(log N)
- Proofs are in the paper

#### Massive failures have little impact



Failed Nodes (Percent)



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# Applications: Chord-based DNS



- DNS provides a lookup service keys: host names values: IP addresses Chord could hash each host name to a key
- Chord-based DNS:
  - no special root servers
  - no manual management of routing information
  - no naming structure
  - can find objects not tied to particular machines

# Summary



- Simple, powerful protocol
- Only operation: map a key to the responsible node
- Each node maintains information about O(log N) other nodes
- Lookups via O(log N) messages
- Scales well with number of nodes
- Continues to function correctly despite even major changes of the system

# **Questions?**





#### **Thanks!**

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