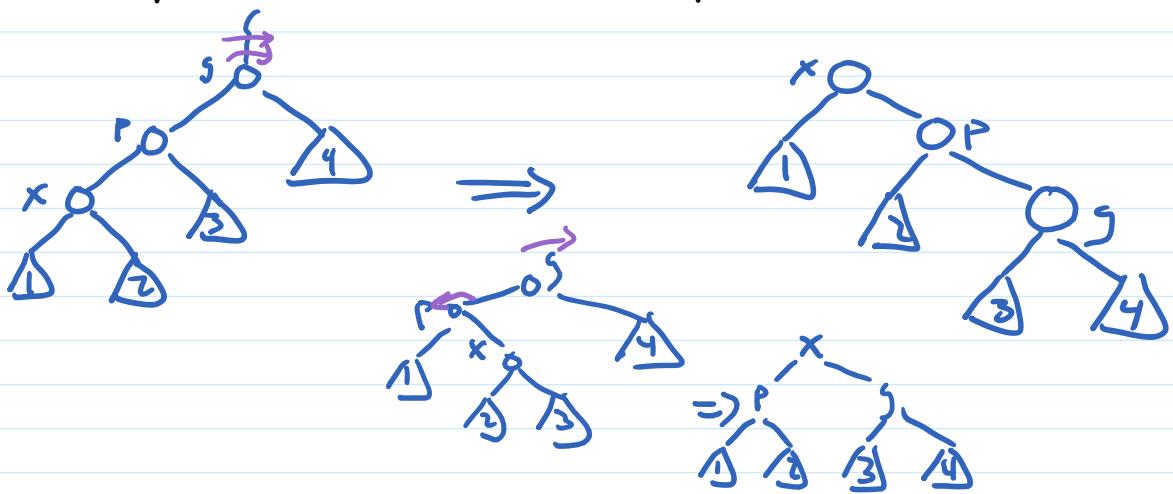
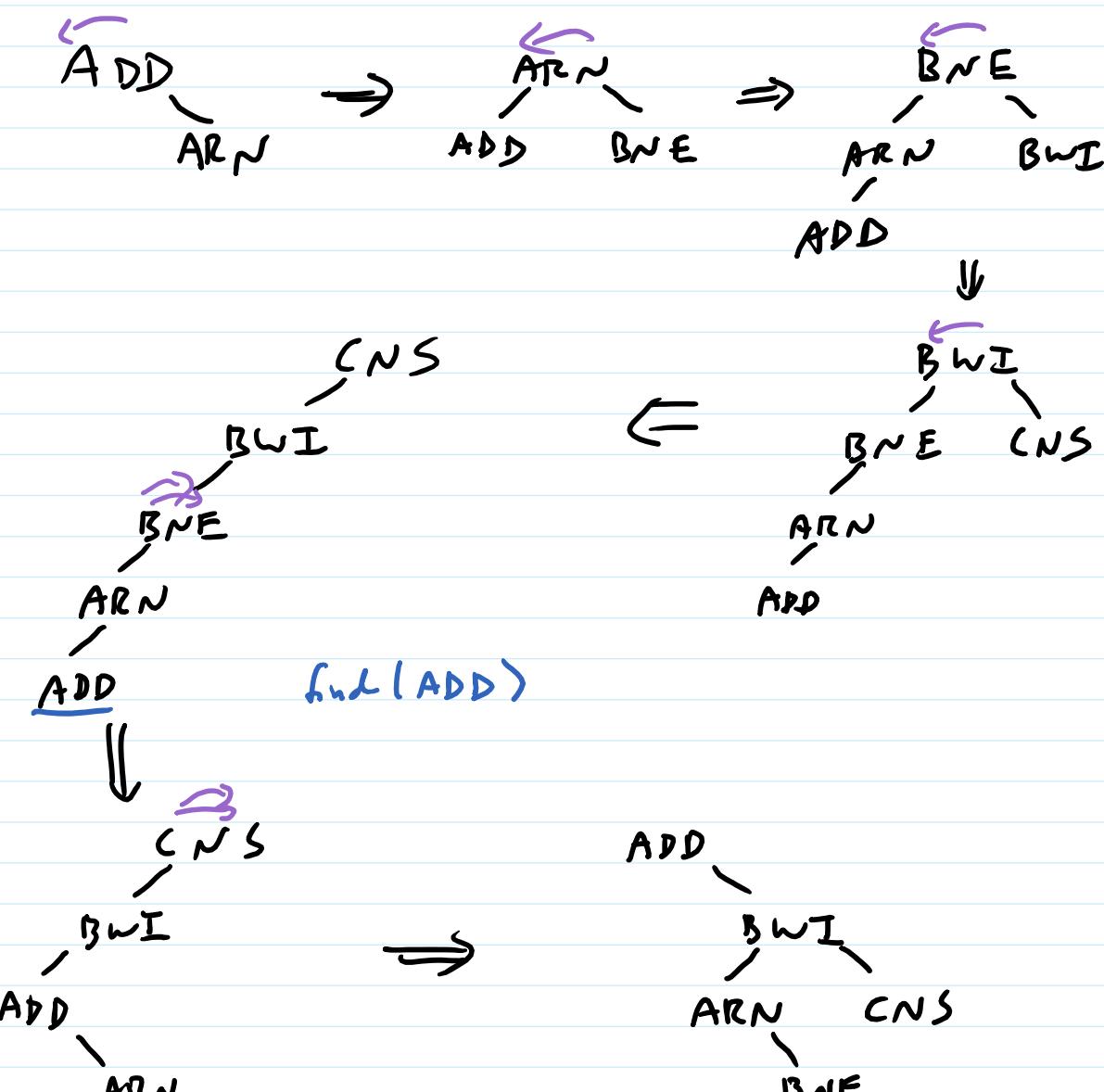


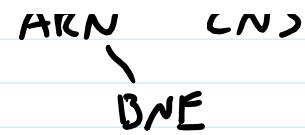
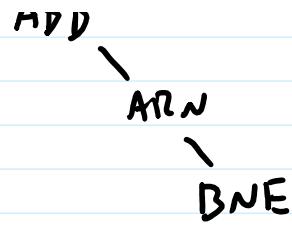
Splay Trees

After any operation, rotate node to top 2 levels at a time



ADD ARN BNE BWI CNS CPT EZE LOS MEX PVG





amortized $O(\log n)$ time
for find/add/remove

BONUS: Frequently accessed nodes
usually near top

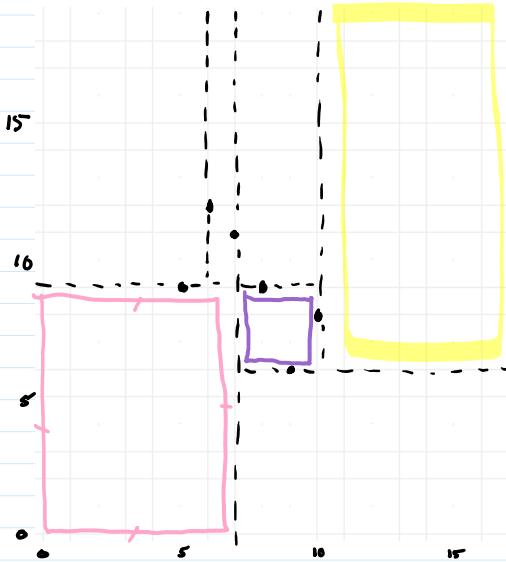
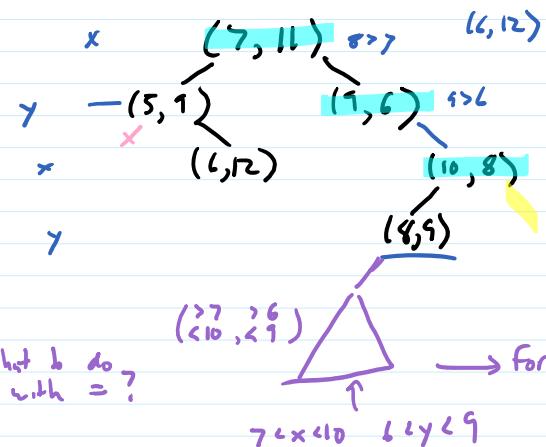
KD-Trees

$k=2$ for 2-D

Binary tree with BST order property rotating through dimensions 15°

levels $0, k, 2k, \dots$ 1st dimension

levels $1, k+1, \dots$ 2nd dimension



For range queries, keep track of bounds on coords of current node
stop when no overlap w/ desired range

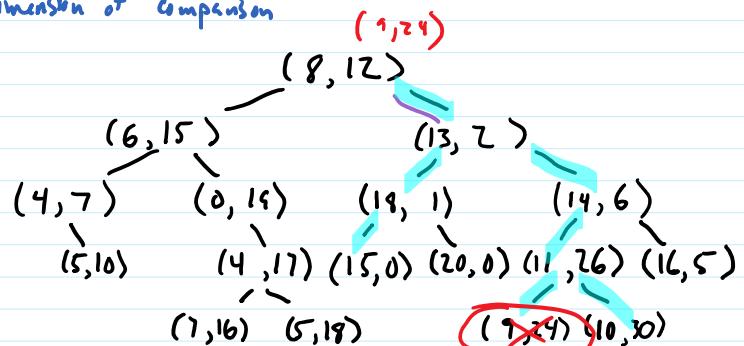
add / find

normalize BST add, but rotate through dimension of comparison

remove

find point to remove

remove (8, 12)



every 2 levels we reduce to 2 subproblems of size $\frac{n}{4}$

to find min x value if current splits on y recurse on both children
else recurse on left child

if tree balanced $O(\sqrt{n})$

$$T(n) = 2T\left(\frac{n}{4}\right) + O(1) \xrightarrow{\text{Master Theorem}} T(n) \text{ is } O(n^{\log_2 2})$$

Build

sort on x: EHD BAI (GF)



build right subtree ICLF

build left subtree EHDB

find median by sorting: FCLBI





sort on y: DBHE

build
sort on curr dim $O(n \log n)$
root \leftarrow median,
left \leftarrow build (pts before)
right \leftarrow build (pts after)

really just want median
can find median in expected $O(n)$ [easy]
worst-case $O(n)$ [hard]

$O(n \log^2 n)$ can do better

- 1) sort on x
- 2) sort on y

build(x, y) \longrightarrow

same points
sorted differently

build(cut, other)

root \leftarrow median(cut)

cut_L \leftarrow 1st half of cut
cut_R \leftarrow 2nd half of cut

can do in $O(n)$
(no sort)

other_L \leftarrow pts from other in L
other_R \leftarrow pts from other in R

left \leftarrow build(other_L, cut_L)
right \leftarrow build(other_R, cut_R)

cut EHDBAICLFE
other ECLGDABHIE

DBHE
FCGJ

$$T(n) = 2 T\left(\frac{n}{2}\right) + O(n)$$

$O(n \log n)$