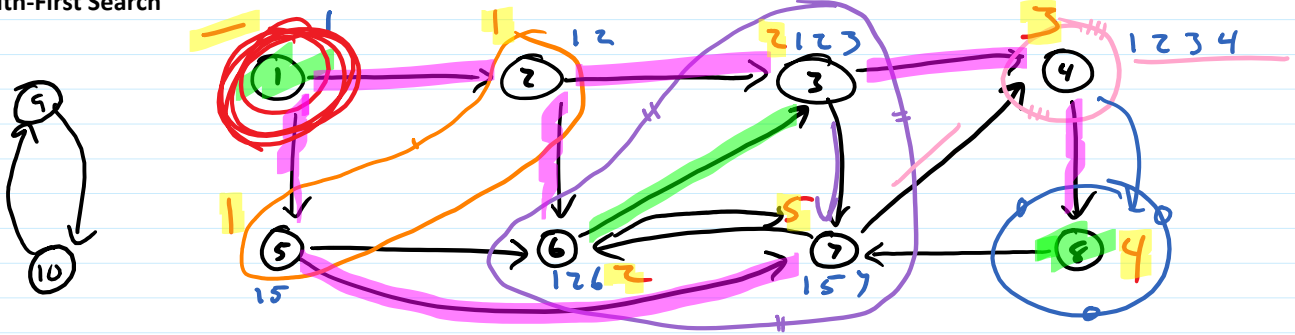


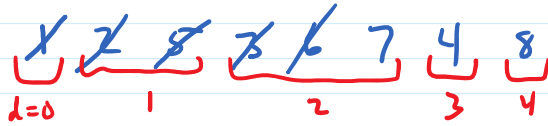
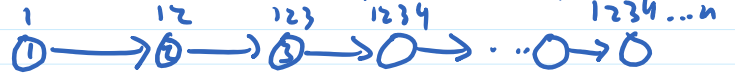
Breadth-First Search



starting from **5**
 + find verts 1 edge from 5
 + find verts 2 edges from 5
 + ...
 + 3 edges
 + 4 edges

1 2 3 4 8

$O(n^2)$ storage if store entire path at each node...



keep track of status unseen / processing / done
 distance
 parent

unseen
 add n verts to queue as we see them

BFS(V, E, from)

```

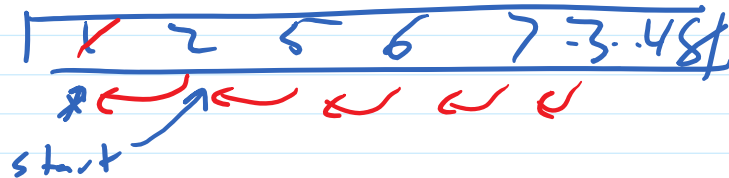
for each vertex u in V
  color[u] <- UNSEEN
  d[u] <- infinity
  parent[u] <- NULL

```

```

color[from] <- PROCESSING
d[from] <- 0
parent[from] <- NULL
Q <- [from]

```



```

while not Q.isEmpty()
  u <- Q.dequeue()
  for each v adjacent to u
    if color[v] == UNSEEN
      parent[v] <- u
      d[v] <- d[u] + 1
      color[v] <- PROCESSING
      Q.enqueue(v)
  color[u] = DONE

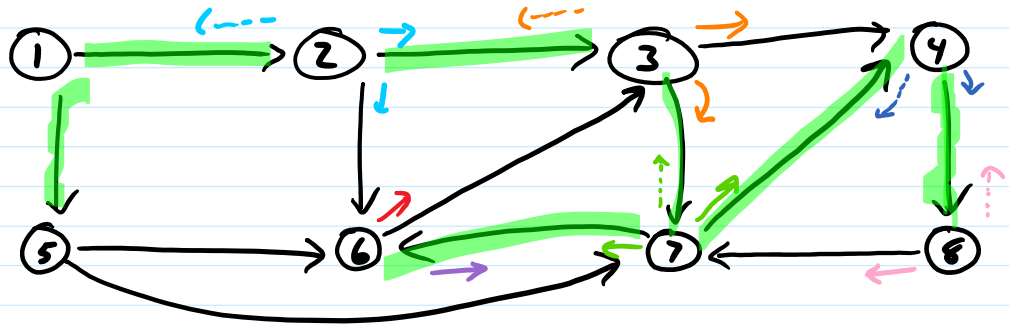
```

$O(n)$ iterations

$O(1)$ (using linked list or array w/ changing start index)

$O(n+m)$ total (another form of for each vertex v for each edge from v)

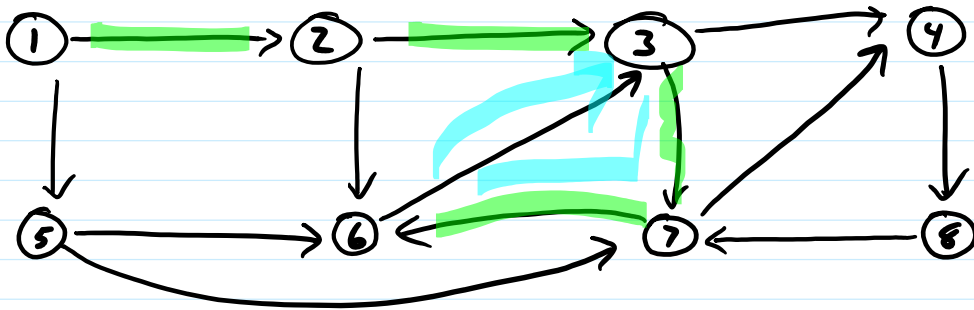
Depth-First Search



Depth-first search: Keep following edges from current vertex
Backtrack when no edges to unvisited vertices

finds cycles (when sees edge to processing vertex)

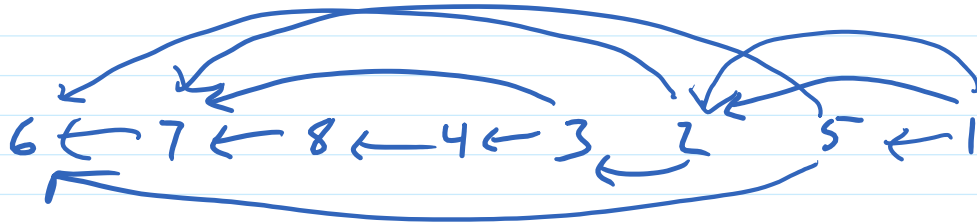
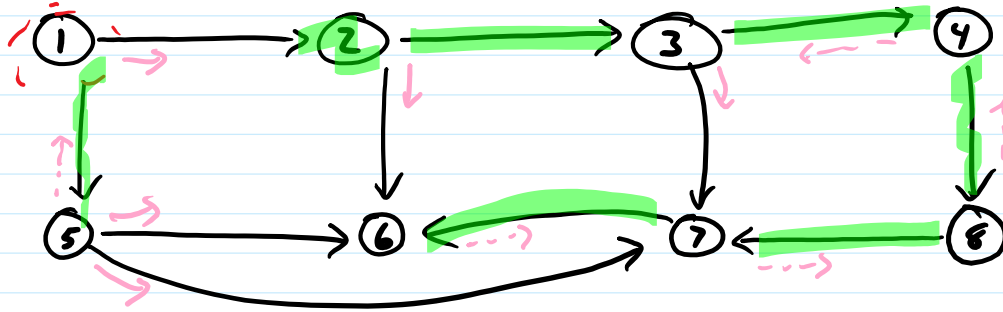
Cycles



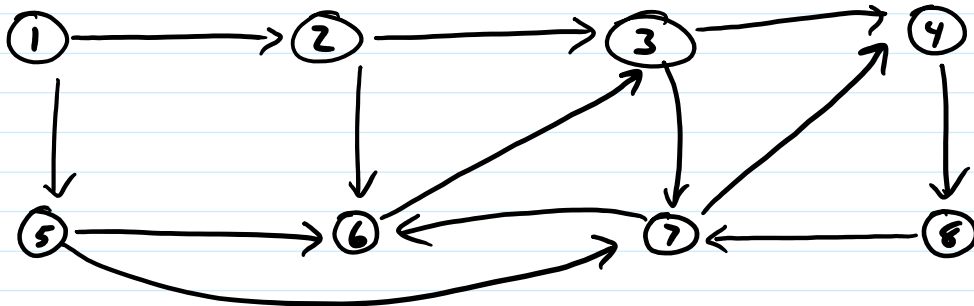
when examining $6 \rightarrow 3$, see that 3 is processing (recursive call not done)
↓
cycle!

Topological Sort - for a directed acyclic graph
orders verts so edges go in one direction

Topological Sort - for a directed acyclic graph orders verts so edges go in one direction



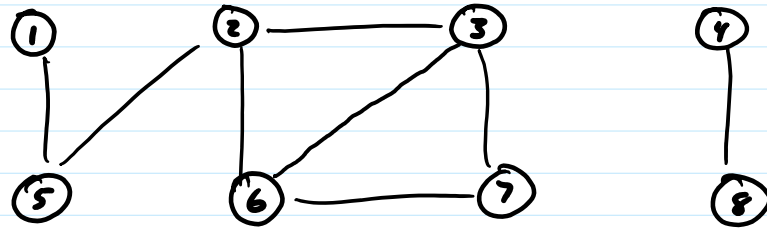
Longest Path



```

DFS-VISIT(G,u)
  color[u] <- PROCESSING
  discovery[u] <- time++
  for each v adjacent to u
    if (color[v] == UNSEEN)
      pred[v] <- u
      DFS-VISIT(G,v)
  finish[u] <- time++
  color[u] <- DONE

```



more useful in DFS-based algos
than distance

```

DFS(G)
  for each u in G.V
    color[u] <- UNSEEN

  time <- 0

  for each u in G.V
    if color[u] = UNSEEN
      DFS-VISIT(G,u)

```

to restart search
at new point when
completely stuck
(useful for some applications
of DFS, including topo sort)