

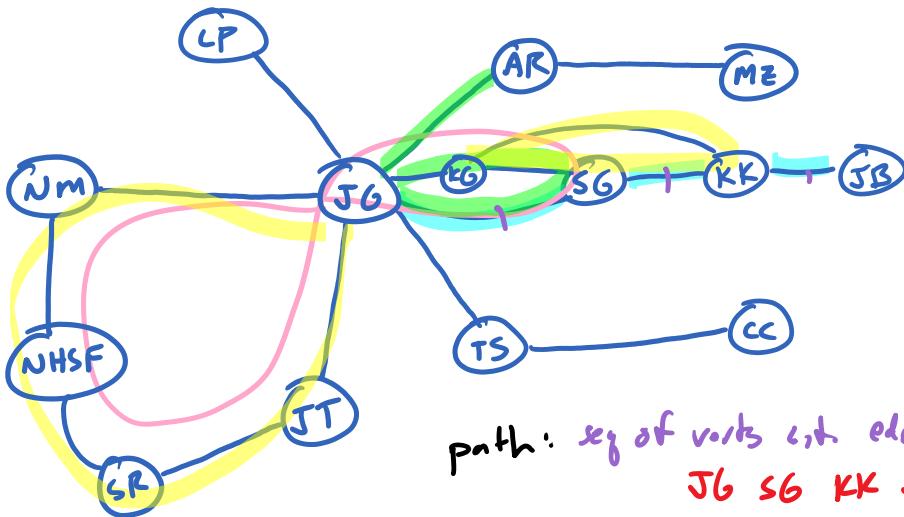
Graphs

↪ representation of things and relationships between them

vertices
people

edges
relationships

undirected



path: seq of verts w/ edge exists between adj verts
JB SG KK JB

simple graph: no self-loops
at most one edge
per pair of verts
(per direction of
a directed graph)

simple path: no repeated vertices not simple
JB SG JB SG KK JB

cycle : path w/ same
start/end JB SG KK JB

simple cycle : only repeat is start/end

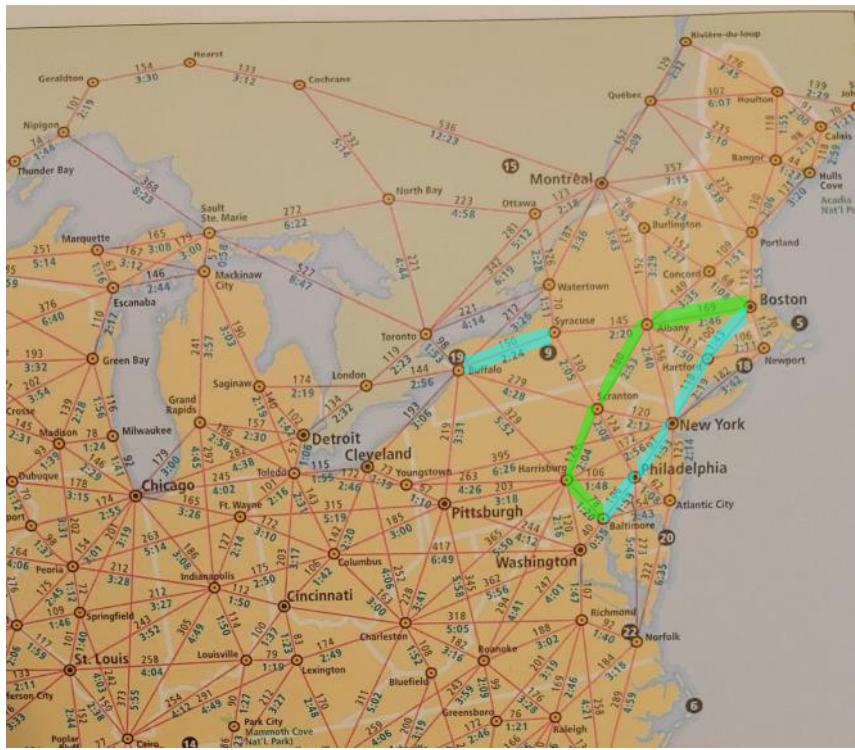
path :

simple path :

cycle :

simple cycle:

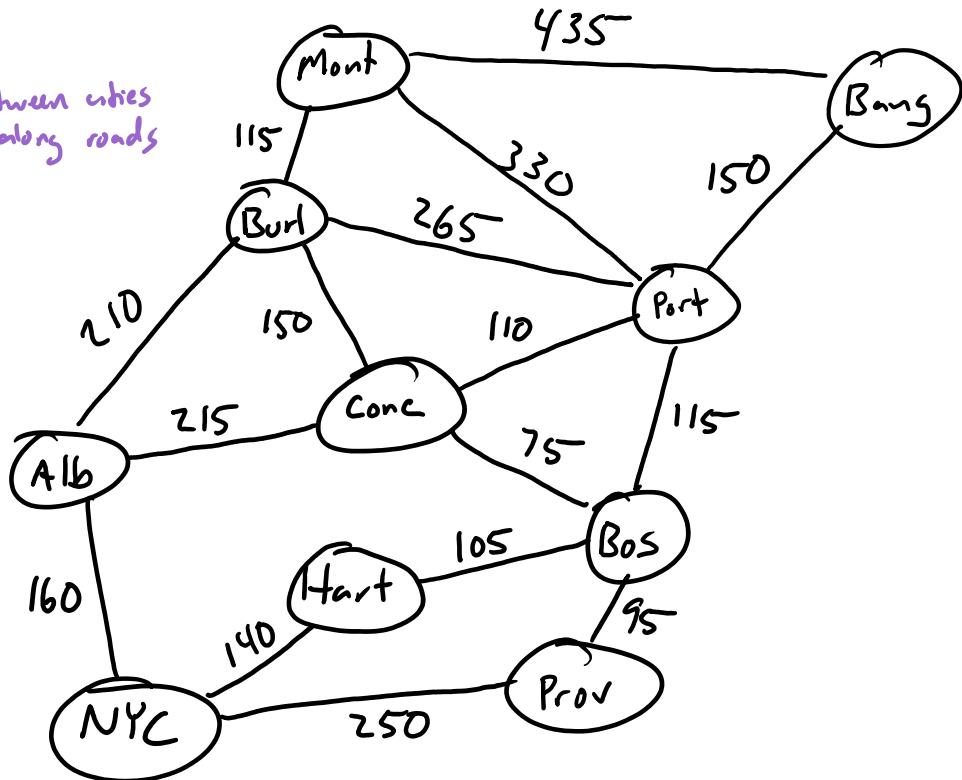
Weighted Graph

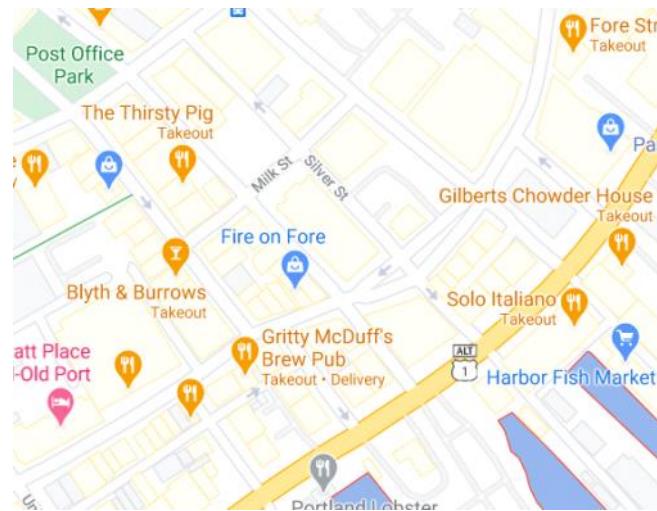
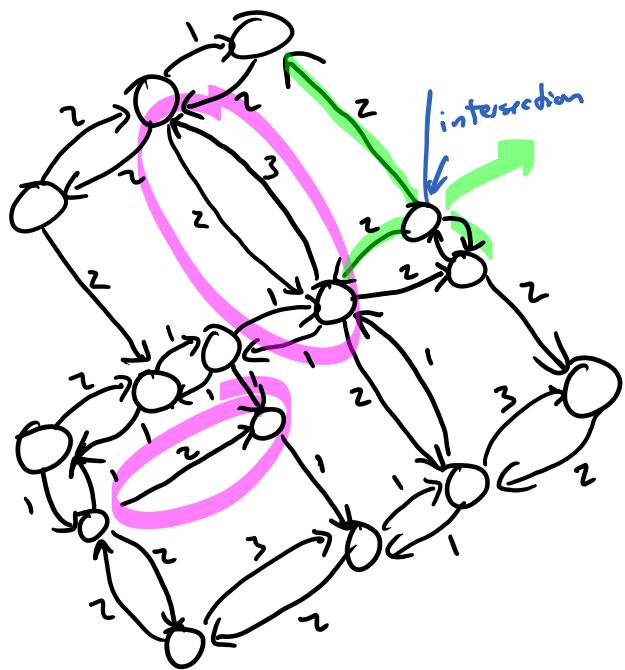


Source: Rand McNally 2012 Road Atlas

each edge labelled with weight

vertex : cities
edges : roads between cities
weights : distance along roads





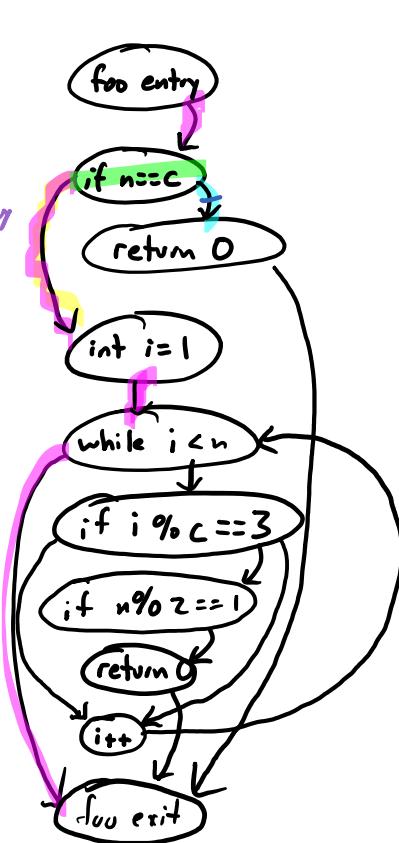
Flow Control Graph

```
int foo(int n, int c)
{
    if (n == c)
    {
        return 0;
    }
    int i = 1;
    while (i < n)
    {
        if (i % c == 3)
        {
            if (n % 2 == 1)
            {
                return 0;
            }
        }
        i++;
    }
}
```

vertices: lines of code
edges: control flow



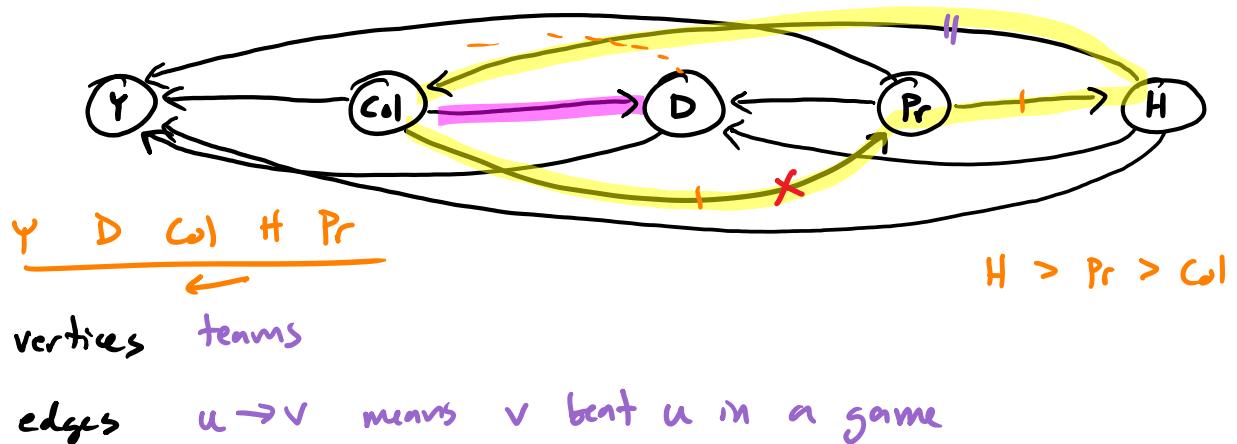
if v might immediately
follow u in some
execution



↗ while ($x \leq 0$)
 $x++;$

is there a path
entry \rightarrow exit
w/ no return statement?

Feedback Arc Set



Feedback Arc Set: what is min num edges you need to remove to make
NP-complete graph acyclic (no cycles)

is there a cycle?

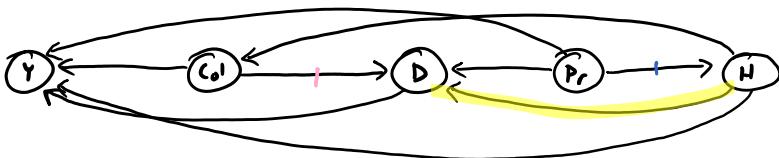
if not, find ordering so all edges go in same dir

if so, find ordering to minimize # of wrong-way edges

brute force: for each possible ordering
Count wrong-way edges
keep track of min wrong-way

$n!$

Graph Representation

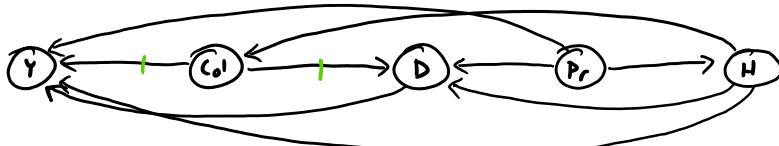


Adjacency Matrix

	0 Y	1 Col	2 D	3 Pr	4 H	keys	values
0 Y	F	T	T	T	T	Y	0
1 Col	T	F	T	F	F	Col	1
2 D	T	F	F	F	F	D	2
3 Pr	T	F	T	F	T	Pr	3
4 H	T	T	T	F	F	H	4

space: $\Theta(n^2)$

unweighted - entries are T/F
weight - entries are weights or "not there"



Adjacency List

(array of lists - one for each vert w/verts at to end
of edge on list)
 n : vertices m : edges

0 Y	:	
1 Col	:	Y ⁰ D ²
2 D	:	Y ⁰
3 Pr	:	Y ⁰ D ² H ⁴
4 H	:	Col ¹ D ² Y ⁰

space: worst case $\Theta(n^2)$
best case $\Theta(n)$
 $\Theta(n+m)$

has-edge (from, to)

adj matrix: array lookup

adj list: seg. search

O(1)

O(n)

Adj Set: use hash table for set representation

0:
1:
2:
3:
4:

add-edge (from, to)

precond: edge doesn't exist

adj matrix: array store $O(1)$

adj list: add to list $O(1)$ amortized

for each edge

adj matrix :

for each row r
for each col c $\Theta(n^2)$
if $\text{adj}[r][c] == \text{T}$
process-edge(r, c)

adj list :

$\Theta(nm)$ $\Theta(n)$
 $\sim \sim$ for [for each vertex u $\Theta(n)$
for each v in adj[u] $\Theta(\text{outdegree}(u))$
process-edge(u, v)]

worst case $\Theta(n^2)$

$\sum_{i=0}^{n-1} (1 + \text{outdegree}(v_i))$

$\Theta(n+m)$
 $\Theta(n)$ for sparse
 $\Theta(n^2)$ for dense

[for each v in $\text{adj}[u]$
 process-edge(u, v)

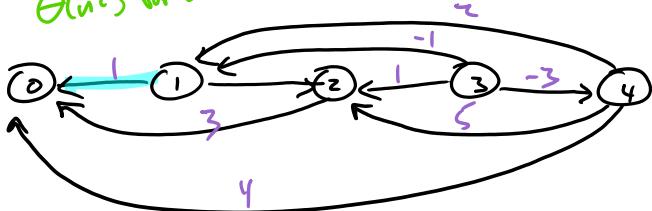
worst case
 $\Theta(\text{outdegree}(u))$

dist vector
 $0:$
 $1: \{0, 1\}$
 $2:$
 $3:$
 $4:$

weight

sparse: $m \in \Theta(n)$

dense: $m \in \Theta(n^2)$



$$\begin{aligned}
 & \sum_{i=0}^{n-1} (1 + \text{outdegree}(v_i)) \\
 &= \sum_{i=0}^{n-1} 1 + \sum_{i=0}^{n-1} \text{outdegree}(v_i) \\
 &= n + m
 \end{aligned}$$

Graph Implementation Time/Space Complexity

	Adj Matrix	Adj List	Adj Set (Hash)
Space	$\Theta(n^2)$	$\Theta(n+m)$	$\Theta(n+m)$
has_edge(<u>s, v</u>)	$O(1)$	$O(n)$	$O(1)$ expected
add_edge	$O(1)$	$O(1)$	$O(1)$ expected
for_each_out-neighbor	$O(n)$	$O(n)$ worst	$O(n)$ worst
for each edge for each vertex for each_out-neighbor	$\Theta(n^2)$	$\Theta(n+m)$	$\Theta(n+m)$