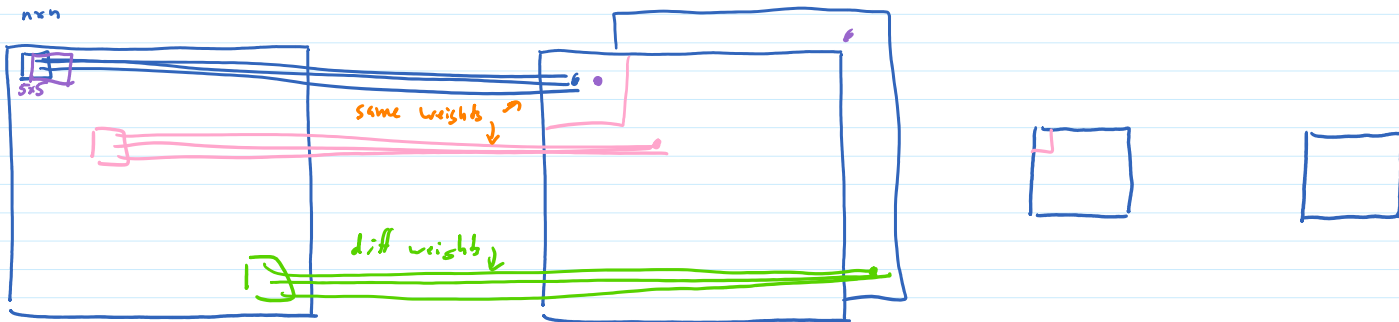
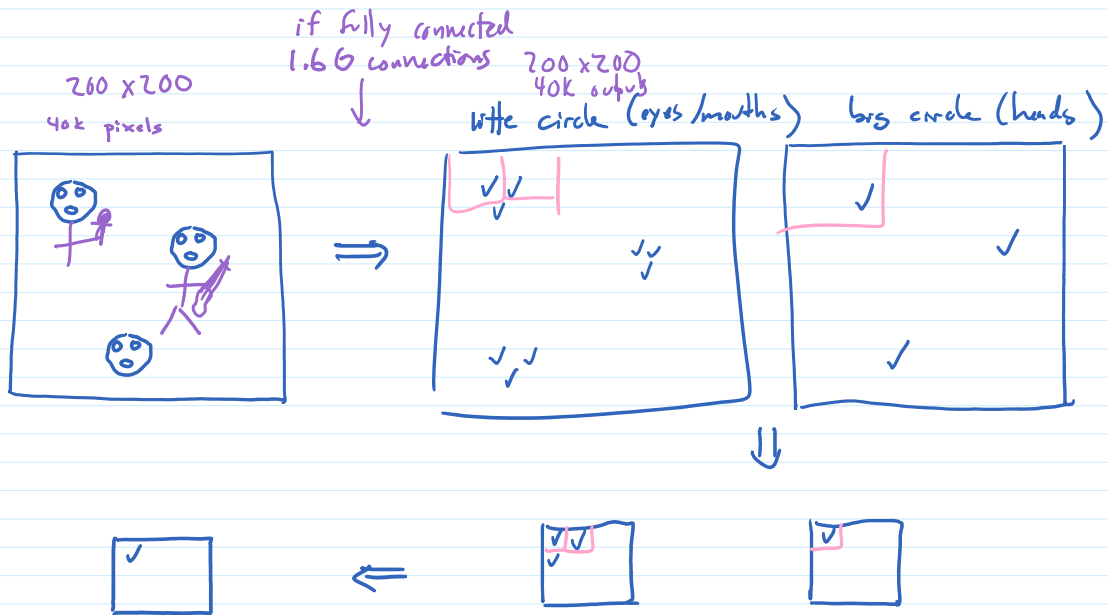
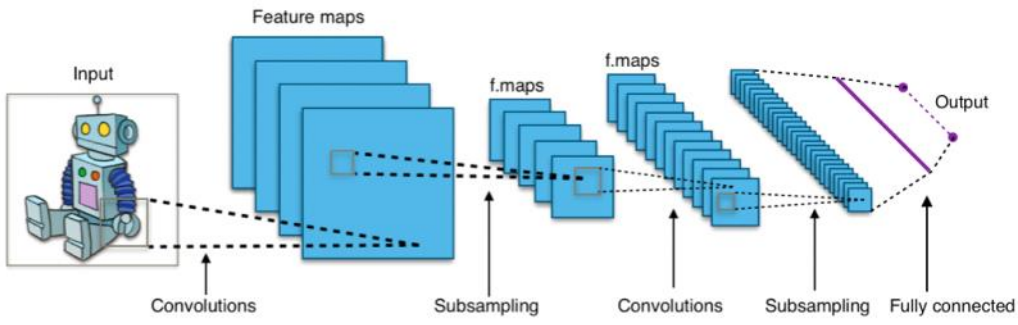


# Convolutional Neural Networks



A much better picture from Wikipedia user [caphox34](#), who does not endorse these notes.



[https://upload.wikimedia.org/wikipedia/commons/6/63/Typical\\_cnn.png](https://upload.wikimedia.org/wikipedia/commons/6/63/Typical_cnn.png)

# AlphaGo

policy network - outputs confidence in each possible move

value network - outputs confidence that position is a winning position

inputs: for each position on board

black or white	2
# stones captured	8
opponent own	8
	8

features deemed important by experts

- liberties
- ladder capture
- escape

Step 1: supervised learning for convolutional deep neural network (policy network)

3 weeks

match expert play 55% match

+ smaller, faster network

Step 2: reinforcement learning for convolutional deep neural network (policy network)

1 day

beats SL net from Step 1 80%

Step 3: reinforcement learning for value network

play step 2 RL network against itself 30M times

1 pos from each game

1 week

Step 4: MCTS  
5 sec/move

modified UCB

$$Q(s,a) + c \cdot \frac{P(s,a)}{1+N(s,a)} \cdot \frac{\sqrt{\sum_b N(s,b)}}{1+N(s,a)}$$

↑  
from SL policy network

when expand a node, initialize Q using value network from step 3

playouts use first step policy SL network

AlphaGo Zero — uses no expert knowledge

Inputs  $19 \times 19 \times 17$  → white/black for current pos + 7 previous  
+ all 1's if black's move  
all 0's if white's turn

Architecture

Outputs — policy and value

